

Bifurcation Analysis of Predator-Prey Systems with Constant Rate Harvesting Using Non-Standard Discretization

G. H. Erjaee¹, Shiraz University, Shiraz, Iran

Color figures available:

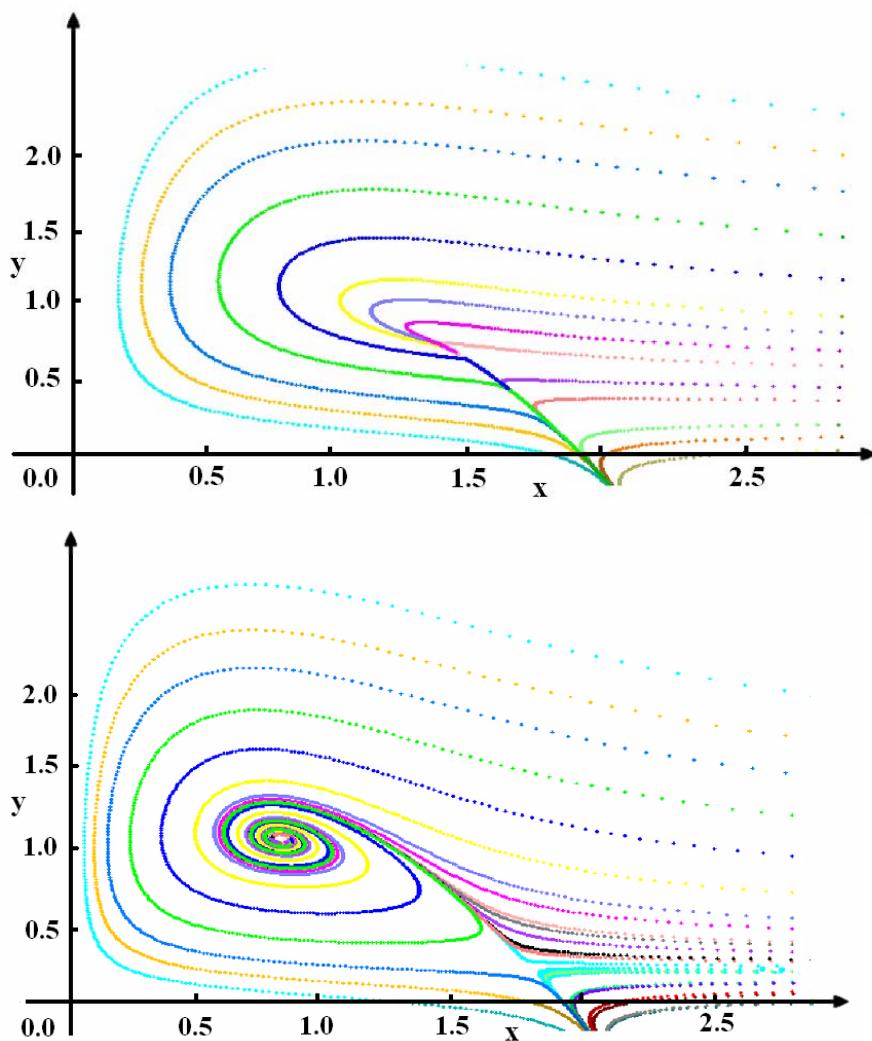
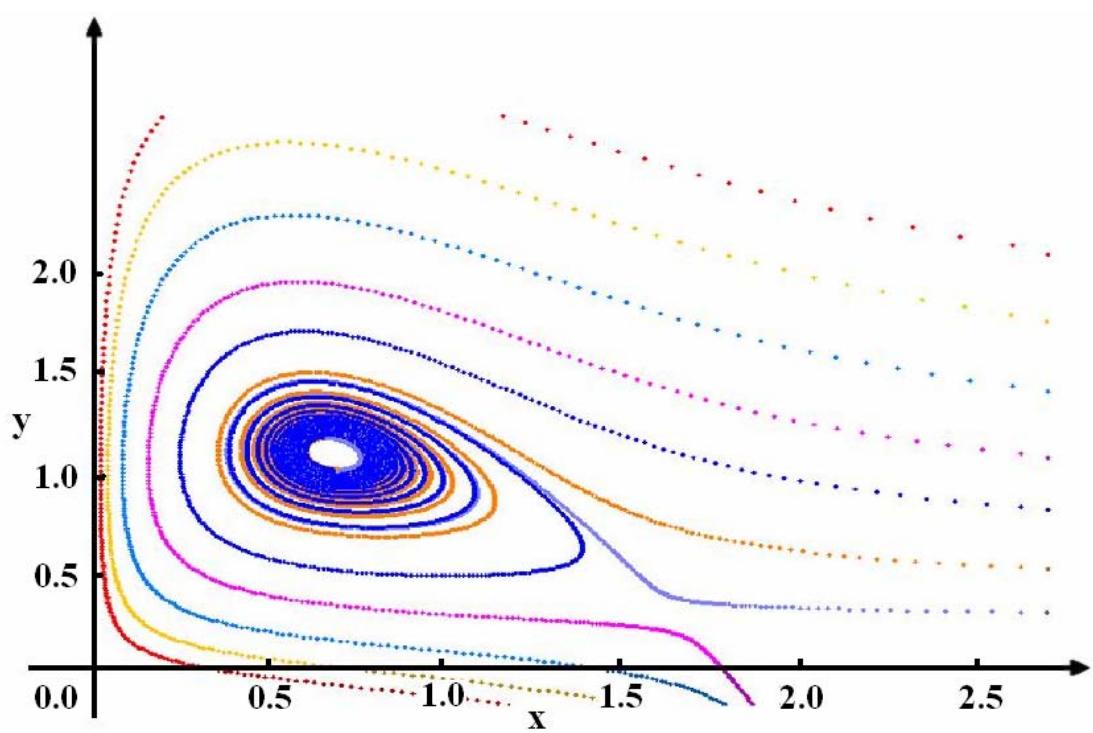
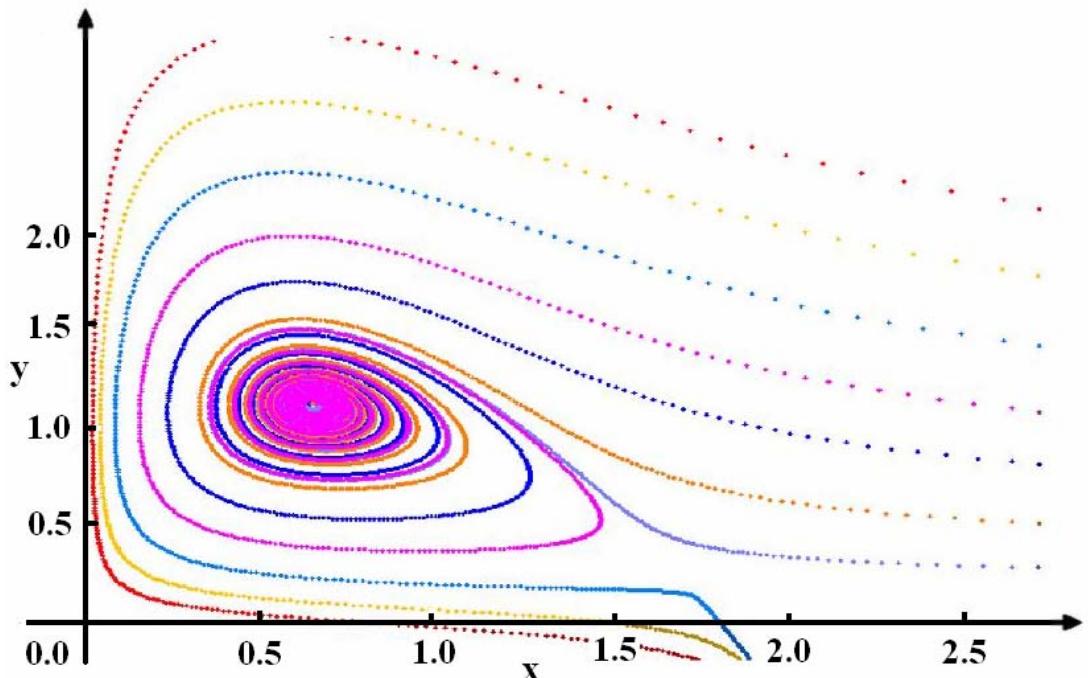


Fig. 2. (a) Unstable saddle-node at bifurcation parameters $d = 0.5$ and $h = 0.0625$, corresponding to the Fig. 1a. (b) Two positive fixed points at bifurcation parameters $d = 0.4$ and $h = 0.06$, a focus and a saddle, respectively, corresponding to the Fig. 1b.

¹ Correspondence address: Mathematics & Physics Department, Qatar University, P. O. Box 2713, Doha, Qatar. Email: erjaee@qu.edu.qa



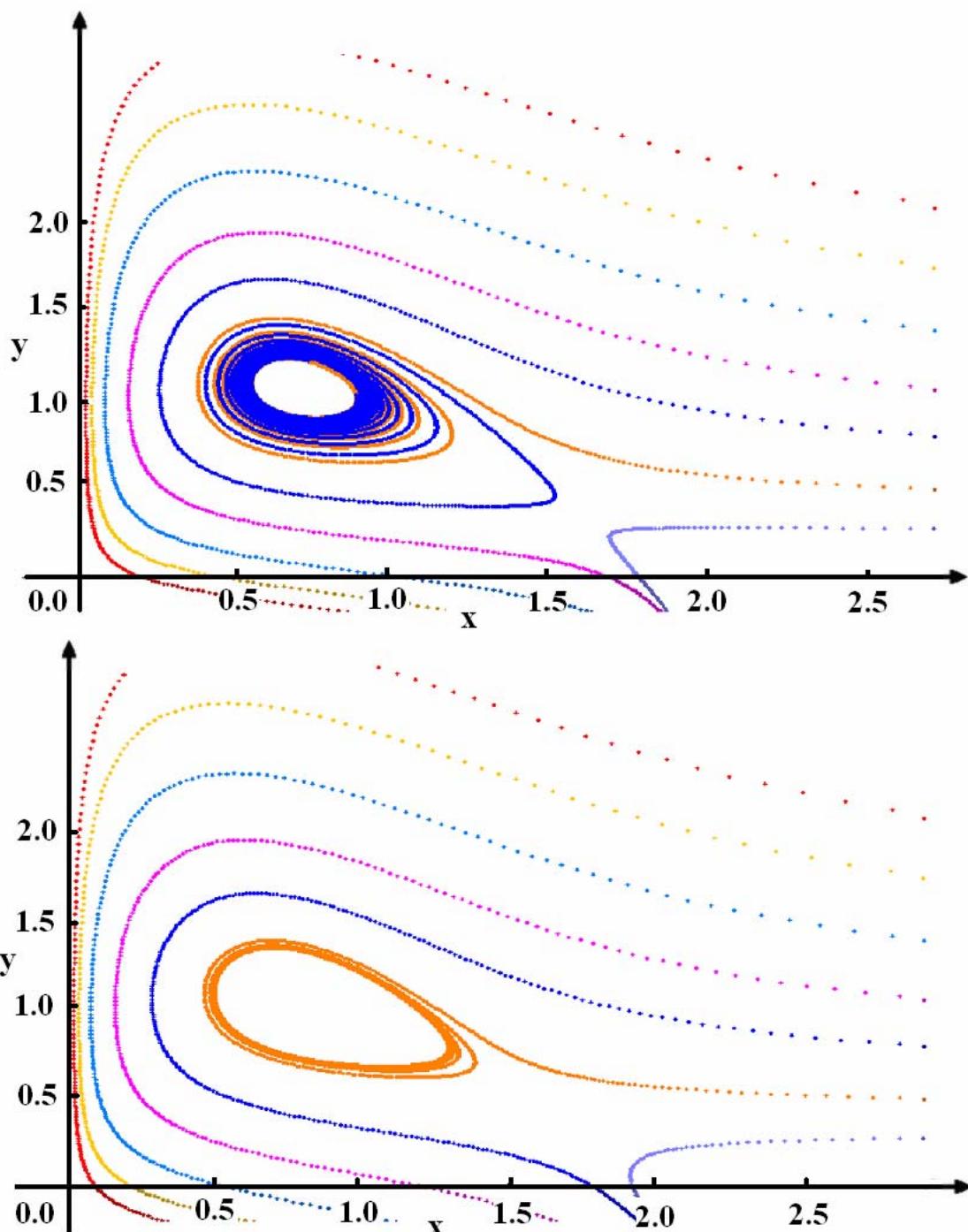


Fig. 3. (a) Hopf bifurcation point at $(x^*, y^*) = (0.7109708, 1.102746)$ for the parametric values $(h_0, d_0) = (0.05, 0.3701951)$. (b) Limit cycle at $(x^*, y^*) = (0.73990351, 1.1096223)$ for the parametric values $(h_0, d_0) = (0.08, 0.352276)$.

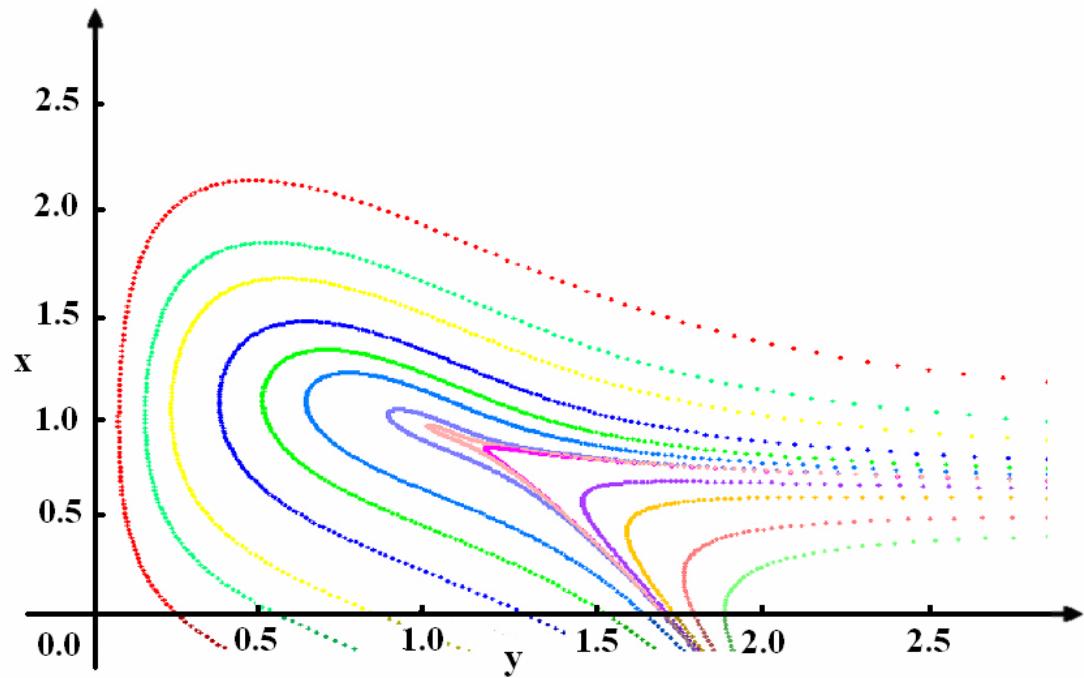


Fig. 4. Takens-Bogdanov point at $(x^*, y^*) = (0.9319796, 1.031697)$ for the parametric values $(h_0, d_0) = (0.30940, 1845761)$.